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学位 (博士) 論文要旨

(Doctoral thesis abstract)

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論文題目	Operator-based robust nonlinear control of uncertain wireless
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論文要旨(2000字程度) (Abstract(400 words))

ABSTRACT

This dissertation provides the operator-based robust nonlinear control design schemes for uncertain wireless power transfer (WPT) systems which is driven by the switch.

Firstly, a robust nonlinear control method is proposed to tackle the uncertain mutual inductance using sliding mode control method, the operator-based right coprime factorization is adopted to guarantee the robust stability of the feedback nonlinear system. Simulations and experiments are tested to verify its effectiveness. Secondly, a new operator-based nonlinear robust control design scheme for WPT systems with uncertainties is proposed, where, from different viewpoint, the considered nonlinear system was of Input-Output presentation. The robust stability can be guaranteed by using operator-based robust right coprime factorization approach. Moreover, the tracking performance is improved by using the proposed control design scheme. Simulations and experiments are tested to verify its effectiveness. Thirdly, an operator-based optimal equivalent load tracking control scheme is proposed for WPT systems with uncertainties. In this control design system, the robust stability of the feedback nonlinear control system is guaranteed by using robust right coprime factorization approach. Especially, the impedance matching of the WPT system could be obtained, thus high efficiency can be obtained. Moreover, the desired output voltage can be obtained in the WPT system. The effectiveness of the proposed control schemes is confirmed by using simulations.